

Non-Gaussian bias from peak-background split

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VD, Crocce, Scoccimarro, Sheth (2010)

VD, Jeong, Schmidt (in prep)

Peak-background split (I)

- Local (Lagrangian) bias:

$$\langle \delta_g | \delta_l \rangle(\mathbf{x}) \equiv \frac{n_g(\mathbf{x} | \delta_l)}{\bar{n}_g} - 1 = \sum_{N=0}^{\infty} \frac{b_N(R_s)}{N!} [\delta(R_l, \mathbf{x})]^N$$

- Take the limit $R_l \gg R_s$:

$$b_N = \left(-\frac{1}{\sigma_{0s}} \right)^N \bar{n}^{-1} \frac{\partial^N \bar{n}}{\partial \nu^N}, \quad \nu \equiv \delta_c / \sigma_0(R_s)$$

(Bardeen et. al. 1986; Cole & Kaiser 1989; Mo & White 1996; Sheth & Tormen 1999;...)

The peaks model

- Galaxies/halos trace local density maxima of the evolved mass distribution -> include the peak constraint
- Lagrangian bias -> study local maxima of the initial, Gaussian density field

(Peacock & Heavens 1985; Bardeen et al 1986; ...)

Peaks 2-point correlation

$$\xi_{\text{pk}}(\nu, R_s, r) = \left(\tilde{b}_I^2 \xi_s \right)(r) + \frac{1}{2} \left(\xi_s \tilde{b}_{II}^2 \xi_s \right)(r) \\ + \text{other 2nd order terms} + \dots$$

where

$$\tilde{b}_I(\nu, R_s, k) = \tilde{b}_{10}(\nu, R_s) + \tilde{b}_{01}(\nu, R_s) k^2$$

$$\tilde{b}_{II}(\nu, R_s, k_1, k_2) = \tilde{b}_{20}(\nu, R_s) + \tilde{b}_{11}(\nu, R_s) (k_1^2 + k_2^2) + \tilde{b}_{02} k_1^2 k_2^2$$

(VD, Crocce, Scoccimarro, Sheth 2010)

Peak-background split (II)

- The scale-independent pieces are the peak-background split bias, i.e.

$$\tilde{b}_{N0}(\nu, R_s) = \left(-\frac{1}{\sigma_{0s}}\right)^N \bar{n}_{\text{pk}}^{-1} \frac{\partial^N \bar{n}_{\text{pk}}}{\partial \nu^N} \equiv b_N(\nu, R_s)$$

- However, derivatives of the peaks number density cannot produce the k-dependent bias terms like

$$\tilde{b}_{01}, \tilde{b}_{11} \text{ etc.}$$

Peak-background split (III)

- Consider another implementation of the peak-background split, in which the dependence of the mass function on the background overdensity is derived explicitly

Conditional peaks number density

$$\bar{n}_{\text{pk}}(\nu, R_s | \delta_l, R_l) = \frac{G_0(\tilde{\gamma}_1, \tilde{\gamma}_1 \tilde{\nu})}{(2\pi)^{3/2} R_1^3} \frac{\exp \left[-(\nu - \epsilon \nu_l)^2 / 2 (1 - \epsilon^2) \right]}{\sqrt{2\pi (1 - \epsilon^2)}}$$

where

$$\nu_l \equiv \frac{\delta_l}{\sigma_{0l}}, \quad \langle \nu \nu_l \rangle \equiv \epsilon = \frac{\sigma_{0x}^2}{\sigma_{0s} \sigma_{0l}}, \quad \langle u \nu_l \rangle \equiv \gamma_1 \epsilon r, \quad r \equiv \frac{\langle k^2 \rangle_x}{\langle k^2 \rangle_s} = \frac{\sigma_{1x}^2 / \sigma_{1s}^2}{\sigma_{0x}^2 / \sigma_{0s}^2}$$

$$\langle u | \nu, \nu_l \rangle \equiv \tilde{\gamma}_1 \tilde{\nu} = \gamma_1 \nu \left(\frac{1 - \epsilon^2 r}{1 - \epsilon^2} \right) - \gamma_1 \left(\frac{1 - r}{1 - \epsilon^2} \right) \epsilon \nu_l$$

$$\text{Var}(u | \nu, \nu_l) \equiv 1 - \tilde{\gamma}_1^2 = 1 - \gamma_1^2 \left[1 + \epsilon^2 \frac{(1 - r)^2}{1 - \epsilon^2} \right]$$

and

$$\sigma_{n_x}^2 \equiv \frac{1}{2\pi^2} \int_0^\infty dk k^{2(n+1)} P_\delta(k) W(kR_s) W(kR_l)$$

- Take $\varepsilon \rightarrow 0$, retain the r dependence and expand

$$\langle \delta_{\text{pk}} | \delta_l \rangle \equiv \frac{\bar{n}_{\text{pk}}(\nu, R_s | \delta_l, R_l)}{\bar{n}_{\text{pk}}(\nu, R_s)} - 1$$

in powers of δ_l :

$$\begin{aligned} \langle \delta_{\text{pk}} | \delta_l \rangle = & \left[\frac{\sigma_{0\times}^2}{\sigma_{0l}^2} \tilde{b}_{10} + \frac{\sigma_{1\times}^2}{\sigma_{0l}^2} \tilde{b}_{01} \right] \delta_l \\ & + \frac{1}{2} \left[\left(\frac{\sigma_{0\times}^2}{\sigma_{0l}^2} \right)^2 \tilde{b}_{20} + 2 \left(\frac{\sigma_{0\times}^2}{\sigma_{0l}^2} \right) \left(\frac{\sigma_{1\times}^2}{\sigma_{0l}^2} \right) \tilde{b}_{11} + \left(\frac{\sigma_{1\times}^2}{\sigma_{0l}^2} \right)^2 \tilde{b}_{02} \right] \delta_l^2 \\ & + \dots \end{aligned}$$

- Cross-correlate with δ_l :

$$\langle \delta_{\text{pk}} \delta_l \rangle = \frac{1}{2\pi^2} \int_0^\infty dk k^2 \left(\tilde{b}_{10} + \tilde{b}_{01} k^2 \right) P_\delta(k) W(kR_s) W(kR_l) + \dots$$

Non-Gaussian halo bias

- Can we derive the non-Gaussian bias factors from the (non-Gaussian) conditional mass function ?

(VD, Jeong, Schmidt, in prep)

- The goal is to expand

$$\langle \delta_{\text{pk}} | \delta_l \rangle_{\text{NG}} \equiv \frac{\bar{n}_{\text{NG}}(\nu, R_s | \delta_l, R_l)}{\bar{n}_{\text{NG}}(\nu, R_s)} - 1 = \frac{\frac{d}{dM_s} \int_{\nu}^{\infty} dx P_{\text{NG}}(x, R_s | \delta_l, R_l)}{\frac{d}{dM_s} \int_{\nu}^{\infty} dx P_{\text{NG}}(x, R_s)} - 1$$

in powers of δ_l

- Use the relation

$$P_{\text{NG}}(\mathbf{y}) = \exp \left[\sum_{N=3}^{\infty} \frac{(-1)^N}{N!} \sum_{\mu_1 \cdots \mu_N} \langle y_{\mu_1} \cdots y_{\mu_N} \rangle_c \frac{\partial^N}{\partial y_{\mu_1} \cdots \partial y_{\mu_N}} \right] P_G(\mathbf{y})$$

$P_{\text{NG}}(\nu, R_s)$ depends on $\langle \nu^N \rangle_c$

$P_{\text{NG}}(\nu, R_s | \delta_l, R_l)$ depends on $\langle \nu^m \nu_l^{N-m} \rangle_c$, $\nu_l = \frac{\delta_l}{\sigma_{0l}}$

- For a Press-Schechter mass function:

$$b_N(\nu) = \frac{1}{\sigma_{0s}^N} \frac{H_{N+1}(\nu)}{\nu}$$

- Define the quantity

$$\Sigma_{\times}^2 \equiv \frac{1}{2\pi^2} \int_0^{\infty} dk k^2 P_{\phi}(k) \mathcal{M}(k, R_s) \mathcal{M}(k, R_l) \mathcal{S}(k, R_s, R_l)$$

$$\delta_R(\mathbf{k}) = \mathcal{M}(k, R) \Phi(\mathbf{k})$$

For instance: $\mathcal{S}(k, R_s, R_l) = k^2 \Rightarrow \Sigma_{\times}^2 \equiv \sigma_{1\times}^2$

$$\mathcal{S}(k, R_s, R_l) = \mathcal{M}(k, R_s)^{-1} \int \frac{d^3 q}{(2\pi)^3} \mathcal{M}(q, R_s) \mathcal{M}(|k\hat{\mathbf{z}} + \mathbf{q}|, R_s) \frac{\xi_{\Phi}^{(3)}(k\hat{\mathbf{z}}, \mathbf{q}, -k\hat{\mathbf{z}} - \mathbf{q})}{P_{\phi}(k)}$$

$$\Rightarrow \Sigma_{\times}^2 \equiv \sigma_{0s}^2 \sigma_{0l} \langle \nu^2 \nu_l \rangle$$

- On taking the limit $R_l \rightarrow \infty$, only the terms with $S=S(k,R_s)$ survive
- Assuming the primordial N -point function dominates,

$$\langle \delta_{pk} | \delta_l \rangle_{NG} \approx \left(\frac{\sigma_{0x}^2}{\sigma_{0l}^2} \right) b_I \delta_l + \left(\frac{\sigma_{0x}^2}{\sigma_{0l}^2} \right) g \left[\langle \nu^N \rangle'_c, \langle \nu^N \rangle_c \right] \delta_l \\ + \frac{1}{(N-1)!} \left[\langle \nu^{N-1} \nu_l \rangle'_c H_{N-2}(\nu) + \langle \nu^{N-1} \nu_l \rangle_c H_{N-1}(\nu) \right] \frac{\delta_l}{\sigma_{0l}}$$

- The scale-dependent bias correction Δb_K can be read off from the terms involving

$$\langle \nu^{N-1} \nu_l \rangle_c \equiv \Sigma_{\times}^2 / (\sigma_{0s}^{N-1} \sigma_{0l})$$

and its derivative

General formula

$$\Delta b_{\text{I}}(k) = \frac{4}{(N-1)!} \left\{ b_{N-2} \delta_c + b_{N-3} \left[3 - N + \frac{\partial \mathcal{F}_s^{(N)}(k)}{\partial \ln \sigma_{0s}} \right] \right\} \mathcal{F}_s^{(N)}(k) \mathcal{M}(k, R_s)^{-1}$$

where

$$\mathcal{F}_s^{(N)}(k) = \frac{1}{4\sigma_{0s}^2 P_\phi(k)} \left\{ \prod_{i=1}^{N-2} \int \frac{d^3 k_i}{(2\pi)^3} \mathcal{M}(k_i, R_s) \right\} \mathcal{M}(q, R_s) \xi_{\Phi}^{(N)}(\mathbf{k}_1, \dots, \mathbf{k}_{N-2}, \mathbf{q}, \mathbf{k})$$

e.g., for $g_{\text{NL}} \phi^3$ (in low- k limit):

$$\Delta b_{\text{I}}(k) = \frac{1}{2} g_{\text{NL}} \sigma_{0s}^2 S_{s,\text{loc}}^{(3)} \left[b_2 \delta_c + \left(1 + \frac{\partial \ln S_{s,\text{loc}}^{(3)}}{\partial \ln \sigma_{0s}} \right) b_1 \right] \mathcal{M}(k, R_s)^{-1}$$

Summary

- Scale-dependent Gaussian or non-Gaussian bias factors can be computed upon formulating peak-background split in terms of conditional mass functions